

# Fisher Information

Applications in Gradient Descent and Incremental Learning

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# Overview

1. Why Fisher Information?
2. Applications - Natural Gradient
3. Applications - Online Learning
4. Applications - Active Learning

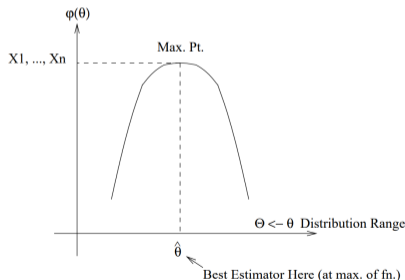
# Revisiting Maximum Likelihood

Given some observations  $x$ , we want to obtain  $\theta$  that maximizes  $f(x|\theta)$ .

With the *i.i.d* assumption, our likelihood function is  $\psi(\theta) = f(x_1|\theta) \times \dots \times f(x_n|\theta)$ .

## Maximum Likelihood Estimate

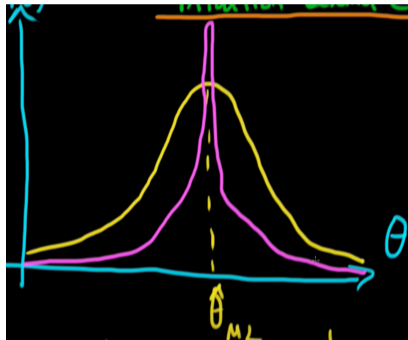
$$\psi(\hat{\theta}) = \arg \max_{\theta} \psi(\theta)$$



Log likelihood makes it easy to obtain  $\hat{\theta} = \arg \max_{\theta} \psi(\theta) = \sum_{i=1}^N \log f(x_i|\theta)$

# Revisiting Maximum Likelihood

Q1. So what after  $\hat{\theta}$ ? How confident are we about our prediction?



Q2. Are we sure about  $\hat{\theta} \rightarrow \theta_0$  as  $n \rightarrow \infty$ ?  
... Fisher Information to the rescue!

# Definition

## Fisher Information

$$\mathcal{I}_\theta = \mathbb{E}_x \left[ \nabla_\theta \log p(x|\theta) \nabla_\theta \log p(x|\theta)^T \right]$$

...

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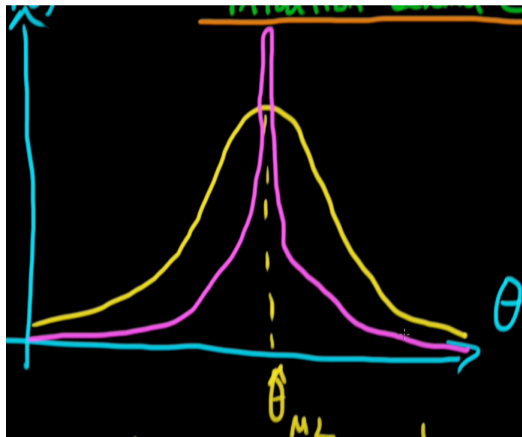
Ye kya hai ?!

1. Asymptotic variance of the log likelihood estimate
2. Sensitivity of the parameter  $\theta$

How !? - Out of syllabus

# Sensitivity of $\theta$

$$\mathcal{I}_\theta = \mathbb{E}_x \left[ \nabla_\theta \log p(x|\theta) \nabla_\theta \log p(x|\theta)^T \right] \equiv -\mathbb{E}_x \left[ \nabla_\theta^2 \log p(x|\theta) \right]$$



# Asymptotic Variance

Once upon a time, there was the Law of Large Numbers:  $P(|\bar{X} - \mathbb{E}(X)| > \epsilon) \rightarrow 0$ .

The Central Limit Theorem defines the rate of convergence:  $P(\bar{X} - \mathbb{E}(X)) \rightarrow \mathcal{N}(0, \frac{\sigma^2}{n})$

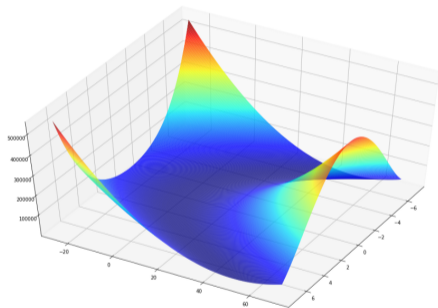
Theorem (Asymptotic Variance of the maximum likelihood estimate)

$$\sqrt{n}(\hat{\theta} - \theta_0) \rightarrow \mathcal{N}(0, \mathcal{I}_{\theta_0}^{-1})$$

# Applications - Natural Gradient

So why is the Hessian important in optimization?

Why do we not use the Hessian in our optimization process?



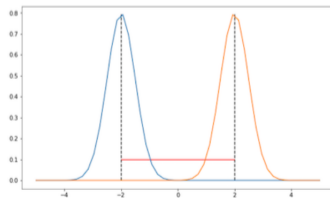
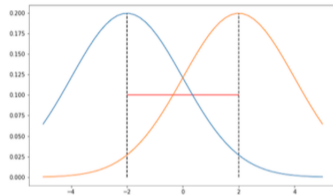
Theorem (Equivalency between Fisher and Hessian)

$$\mathcal{I}_\theta = -\mathbb{E}_{p(x|\theta)}[H_{\log p(x|\theta)}]$$



# Applications - Natural Gradient

So what is Gradient Descent?  $\frac{-\nabla_{\theta}\mathcal{L}(\theta)}{\|\nabla_{\theta}\mathcal{L}(\theta)\|} = \lim_{\epsilon \rightarrow 0} \frac{1}{d} \arg \min_{d < |\epsilon|} \mathcal{L}(\theta + d)$



Parameter space or Distribution space?

# Applications - Natural Gradient

Distribution space: KL Divergence!

Equivalence between KL divergence and Fisher information

$$KL[p(x|\theta)||p(x|\theta + d)] \approx \frac{1}{2}d^T \mathcal{I}_\theta d$$

So a step in the parametric space is replaced by a step in the distribution space!

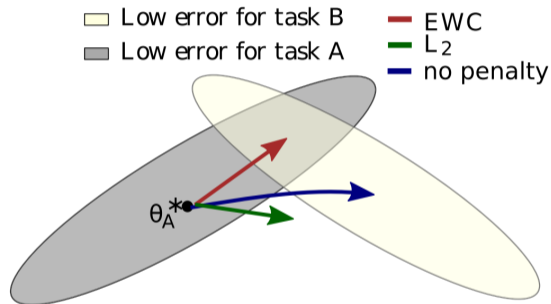
$$\lim_{\epsilon \rightarrow 0} \arg \min_{d < |\epsilon|} \mathcal{L}(\theta + d) \implies \lim_{\epsilon \rightarrow 0} \arg \min_{d: KL[p_\theta || p_{\theta+d}] = \epsilon} \mathcal{L}(\theta + d)$$

Theorem (Natural Gradient)

$$\hat{\nabla}_\theta \mathcal{L}(\theta) = \mathcal{I}_\theta^{-1} \nabla_\theta \mathcal{L}(\theta)$$

So why is Natural Gradient not popular? Ummm, Fisher matrix and inversion is expensive? So can we approximate the Fisher matrix? Yes, as done in *Adam* optimizer!

# Applications - Elastic Weight Consolidation

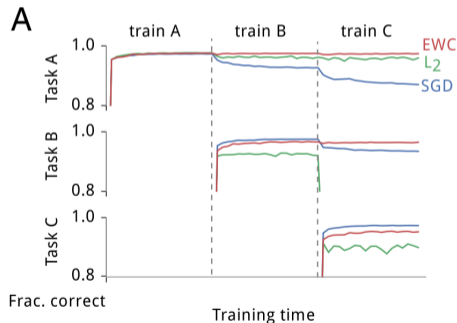


Extending  $\log p(\theta|\mathcal{D}) = \log p(\mathcal{D}|\theta) + \log p(\theta) - \log p(\mathcal{D})$  to tasks  $\mathcal{D}_A, \mathcal{D}_B$ :  
 $\log p(\theta|\mathcal{D}) = \log p(\mathcal{D}_B|\theta) + \log p(\theta|\mathcal{D}_A) - \log p(\mathcal{D}_B)$

# Applications - Elastic Weight Consolidation

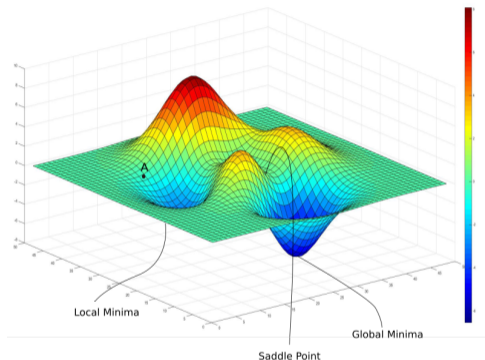
## Theorem (Elastic Weight Consolidation)

$$\mathcal{L}(\theta) = \mathcal{L}_B(\theta) + \sum_i \frac{\lambda}{2} \mathcal{I}_i(\theta - \theta_{A,i}^*)^2$$



"Overcoming catastrophic forgetting in neural networks", PNAS

# Applications - Expected Gradient Length



## Expected Gradient Length - Classification

$$x_{EGL}^* = \arg \max_x \sum_i P(y_i|x; \theta) \|\nabla_{\theta} l(\mathcal{L} \cup (x, y_i); \theta)\|$$

Can we derive this result?

Expected Gradient Length - Classification

$$x_{EGL}^* = \arg \max_x \sum_i P(y_i|x; \theta) \|\nabla_{\theta} l(\mathcal{L} \cup (x, y_i); \theta)\|$$

Fisher to the rescue!

# Applications - Expected Gradient Length

Asymptotic Variance  
$$\sqrt{n}(\hat{\theta} - \theta_0) \rightarrow \mathcal{N}(0, \mathcal{I}_{\theta_0}^{-1})$$

Minimizing the variance is same as maximizing the Fisher Information

$$\max_q \int q(y|x, \theta) \|\nabla_{\theta} l(x, y, \theta)\|^2 dy dx$$

Maximizing  $q$  is same as selecting unlabelled  $x$  having largest gradient

$$x_{EGL}^* = \arg \max_x \sum_i q(y_i|x; \theta) \|\nabla_{\theta} l(x, y_i, \theta)\|^2$$

*"Active Learning for Speech Recognition: the Power of Gradients", NIPS Workshop 2016*

Thank You!

Thank you!